

***Communications and Tracking  
Expert Systems Study***

## Preface

This research was conducted under the auspices of the Research Institute for Computing and Information Systems by T.F. Leibfried, Associate Professor of Computer Science, Terry Feagin, Professor of Computer Science, and David Overland, Research Associate, all at the University of Houston-Clear Lake.

Funding has been provided by the Tracking and Communications Division, within the Engineering Directorate, NASA/JSC through Cooperative Agreement NCC 9-16 between NASA Johnson Space Center and the University of Houston-Clear Lake. The NASA Technical Monitor for this activity is Oron Schmidt, Systems Techniques Section, Communications Performance and Integration Branch, NASA/JSC.

The views and conclusions contained in this report are those of the authors and should not be interpreted as representative of the official policies, either express or implied, of NASA or the United States Government.

RECEIVED

FEB 11 1987

RICIS

INTERIM REPORT

UNIVERSITY OF HOUSTON-CLEAR LAKE

RESEARCH INSTITUTE FOR THE COMPUTING

AND

INFORMATION SCIENCES

RESEARCH ACTIVITY AI-1

COMMUNICATIONS AND TRACKING EXPERT SYSTEMS STUDY

Prepared by:

T. F. Leibfried, Jr., Ph.D. -- Principal Investigator  
T. Feagin, Ph.D. -- Research Area Director  
D. Overland, B.S.M.E. -- Research Associate

In cooperation with:

O. Schmidt -- Technical Monitor/NASA-JSC  
30 January 1987

University of Houston-Clear Lake Research Activity AI-1  
Communications and Tracking Expert Systems Study  
Interim Report for Semester Period Ending 31 Dec 1986

EXECUTIVE SUMMARY

The original objectives of the study consisted of five broad areas of investigation:

1. Criteria and issues for explanation of C & T system anomaly detection, isolation, and recovery;
2. Data storage simplification issues for fault detection expert systems;
3. Data selection procedures for decision tree pruning and optimization to enhance the abstraction of pertinent information for clear explanations;
4. Criteria for establishing levels of explanation suited to needs;
5. Analysis of expert system interaction and modularization.

Progress was made in areas 1, 2, 3 and 5, but to a lesser extent in area 4 during Phase 1.

Among the types of expert systems studied were those related to anomaly or fault detection, isolation and recovery. Specifically, the interim results Harris and TRW T&C expert system studies were examined and work supplementing them with explanation facilities was initiated.

An expert system which is rule based may be thought of as a sequence of if-(condition)-then-(action and fact(s)) statements in an endless repeating loop. A given statement or rule, when its condition has been satisfied and it executes, is said to have "fired". The rule usually asserts "facts" which may satisfy the condition(s) of other if-statements or rules which in turn can assert actions and/or other facts and so on. The beauty of these systems is that they are flexible, easily expanded or modified, succinct, and readily understood by humans. Their problems are a general lack of structure, modularity for groups of related rules, and therefore poor maintainability. Also, in complex rule-based systems there are problems controlling the order in which the rules are applied. That is, a "resolution strategy" must be provided. Most expert systems of this type are each essentially one big program where object-oriented design and information hiding are relatively absent. These latter concepts are essential for data integrity of software systems. This is a major issue for any project as big as the Space Station, where the total software system size may be measured in millions of lines of code. The potential benefits of expert systems are too great to reject them out of hand, especially since the modularity issue is probably tractable. Modularity in such systems is being investigated as part of area number 5 above.

Results to date indicate that modularity is possible especially in the case of predictable expert systems (i.e., systems where rules cannot make new rules). In fact, virtually any predictable expert system is capable of being rewritten in a procedural language. In some case that may be even desirable for part, if not all, of a given system. This was done in this study for a simple subsystem based upon a system simulator written by TRW. The simulator, written in C, was rewritten in Ada. Then, fault diagnosis and explanation facilities were implemented to investigate area number 1 (explanation facility) and area number 5 (interaction and modularization) described above. The source code for this system is in Appendix B as MAIN SIM MOD3.ADA. Results of this portion of the the study are shown in item D of the body of this report. Briefly, the results indicate that, an explanation facility is best structured as an integral part of the system rather than as an appendage. Object-oriented modularization promotes data integrity, and that the capability of retrieving and using old data is probably best achieved through a procedural language. Object-oriented design was first suggested by Parnas and implies that each object (e.g., variable) should be controlled by one module and the resources necessary to modify or change any of its characteristics should reside only within that module.

The areas number 1 (expert explanation), number 2 (storage simplification) and number 3 (decision tree issues) were investigated by the implementation of a simple engine diagnosis program. The source code and concomitant comments for DIAG4.ART are in Appendix A. The results are shown in item B of the body of the report. Briefly, the results show that rules have a taxonomy (e.g., explanation rules, bookkeeping rules, action rules), and that the time stamping of facts is necessary for explanations of any past expert system actions. The need for functional or domain partitioning was one of the discoveries of this investigation.

Not much implementation of techniques for pruning decision trees of irrelevant decision nodes (area number 3) was accomplished; however, these and other data compression concepts were discussed extensively and some paths of investigation and experimentation are indicated. So-called spine optimization of the decision tree may provide a capability for explaining in retrospect how and why a decision has been reached or even perhaps why a particular decision was not reached. (A spine is defined as the conjunction of decisions for which the retrieval is a single conclusion.)

In the relatively short time this study has been in progress, what were originally nebulous issues have become more clear. This is not to say that they have become more tractable, but at least some of the issues are better defined than they were four months ago. We expect that this trend will continue.

BODY OF THE REPORT

## A. Introduction

The original statement of activity objectives consisted of several items summarized as follows:

1. Examination of existing C&T systems configuration and monitoring problems--

The activity started with an examination of fault detection expert systems and historical database storage, which is one facet of the subject area of C&T system anomalous behaviour. An anomalous event may be defined as the situation when normal systems software has been unable to operate according to plan. Some tentative conclusions for structuring these activities have been determined. This activity continues.

2. Audit trail simplification policies--

Some experimental work has been accomplished for this activity. In particular, audit trails for fault detection expert systems have been analyzed. An hypothesis has been formulated, based on preliminary results which indicates that shallow explanations may be able to use a limited audit database but deeper explanation facilities may require a parallel expert system, otherwise the audit trail database might become too cumbersome. The question of the effect of utilizing distributed expert systems on practical explanation facilities has not yet been considered, but that is a subject which will need to be addressed once the resources needed by such facilities have been identified.

3. Data selection procedures--

This activity is closely related to item 2 but has been modified to focus upon decision tree pruning and storage depth of unchosen paths. For explanation purposes one hypothesis to be explored is to store chosen path nodes and one node level below each chosen path node for all unchosen paths. This would, at a minimum, double the storage required for a chosen decision tree but it would obviate the necessity for reexercising a duplicate of parts of the original expert system for shallow explanations. No general rule with specifics has yet been established but some simple subsystem simulations, namely, DIAG4.ART and MAIN\_SIM\_MOD3.ADA, have given some insight into this problem. This activity continues.

4. Criteria development for user-expert system interfaces--

This activity has been modified to focus upon identifying levels of explanation suited to various user's requirements. It will be assumed that user requirements will have already been identified. It will be assumed that short explanations will be supplied initially and that levels of depth may be requested at any point in the process. This activity has not seen much progress to date but will continue in the revised direction.

5. Expert system interaction--

Intercommunication and hierarchical decision priorities have been discussed but no definitive assertions have yet been determined. At first sight this issue seems related to partitioning and modularizing expert systems. This latter issue is one which is to be explored in the next phase of this study.

B. Explanation Facilities and Decision Trees

An explanation facility will be an important part of any system that is used to provide diagnostics for problems that may develop in the tracking and communication systems on the space station. Also, once the most probable source of a problem has been identified and corrective measures are begun, an explanation of why and how such actions have been taken will be necessary. It would appear that there are several levels of explanation that can be provided. At one extreme, a complete explanation with all the intricacies and details of all of the inferences used could be provided, such that the explanation would be effectively equivalent to providing a complete decision tree (in which only one path has been followed). At the other extreme, a brief, superficial explanation could be provided that would only indicate the most immediate reason why a particular path was selected. This might be of use in the case when a systems human monitor might have selected a different alternative than did the expert system and he seeks the reasons for the selection made by said expert system. In this latter case, it would be practical to store the path and the collection of decisions made along the path. However, simply quoting the path to the given conclusion will not, in general, provide a satisfactory explanation because there may be irrelevant decisions on the path and there may be a need for deeper explanations. It appears that the need for deeper explanations can only be satisfied if the complete reasoning process for reaching a given conclusion is available (i.e., either we provide access to all the rules that were used or we provide the complete decision tree). Such might be needed when a large scale manual intervention is planned for direct control of C&T systems and in that case irrelevant decisions would effectively be "noise" in the system. A procedure is available that would permit the removal of irrelevant decisions. It is called spine optimization, which consists of pruning the decision tree to obtain a "prime spine", and which prime spine is formed by delaying or removing irrelevant decision nodes in the tree. Most of the work so far on spines has been theoretical, so it is not clear that the benefits of such removal would justify the costs.

It may be, in some cases, that the option of providing the complete decision tree would not be practical in light of the large amount of storage that this would require for each of many points in the past. It is possible, however, that a few of the most recent decision processes could be stored in their entirety and that a number of older decision processes could be saved in an abbreviated form (perhaps with just a simple rundown on the decision path actually taken with only immediate explanations for taking a particular path provided).

If more elaborate explanations were required for older decisions, then it would still be possible, albeit time-consuming, to reload another knowledge base with the facts that were true at the time of interest and then begin to execute some of the explanation rules over again, only this time with the user interrupting that expert system and asking questions about the decisions which were made.

One of the dilemmas encountered with after-the-fact explanation facilities is that the explanation facility itself must provide some constructive filtering. Indeed, in order to remove irrelevant decision information the explanation program must prune and perhaps redo, albeit with a different perspective, some of what the diagnostic facility did in the first place. The simplest thing to do would be to supply the complete decision tree, but this would be barely one cut above the Automate Reasoning Tool (ART) dribble file as far as user utility is concerned.

An hypothesis or question which probably is worth considering is, "Should the explanation facility 'anticipate' queries so that it would effectively run in parallel to the diagnostic expert facility but without encumbering it?" Another possibility is to initiate the building of a more extensive event data base whenever an anomalous condition occurs.

At this point, without making a definite statement, let us offer a conjecture. We are of the opinion that storing the entire decision tree may be a viable solution, after all. It's not really as bad as storing the entire state at several points in time -- which might be needed since some problems will be building up over time -- in order to be able to provide explanations. The decision tree information would be kept active for a minimal time, presumably until time had passed when an explanation might be required, and then archived. We think that the decision tree also has just those rules used/needed to provide the explanation. If the other approach is used, we would have to ferret out those rules that were relevant or reload the entire expert system.

#### C. The ART Environment and the Attempt to Implement an Elementary Simulation, Diagnostic and Explanation System

##### The ART Environment

There are many advantages and some deficiencies to the Automated Reasoning Tool (ART) environment. The flexibility allows both forward and backward chaining with schema (which provides memory slots similar to frame-based languages), and viewpoints. The viewpoints may provide a way of recalling how a particular expert system operated at a given time in the past. This is something which would be useful for providing an explanation of a past event. Unfortunately, the first diagnostic and explanation example program did not use viewpoints and the lack of the availability of file input-output limited the scope of the program. Useful knowledge was obtained, nevertheless, and that should help the development of future explanation experiments.

### Recommendations on Expert Systems Languages

A few observations have resulted from the first diagnostic-explanation system. The ART language coupled with the Symbolics system is a very versatile, albeit sometimes clumsy, approach to expert system development. The feasibility of developing an in-house (Ada-based) rule-based language should be investigated. This would allow data structures and I/O requirements to be tailored for the application.

This could also allow the development of subprocedure calls for both subprocedures written in sequential languages and those written in the development language (in other words, calling other expert system programs).

### The DIAG4.ART Diagnostic-Explanation Program

#### Objectives

The goal of this program was to demonstrate at least a rudimentary explanation facility on a limited domain, mainly as a means of exploring the concepts involved, and also as a means of learning the ART language and Symbolics system.

#### Description

The program, written in ART, simulates the operation of a four-stroke, two-valve, single-piston internal-combustion engine. It also diagnoses failures in the ignition phase of the engine operation, and implements corrective action. It is then capable of explaining the diagnosis and the corrective action taken.

The program was also written so as to reflect some logical organization: The explanation rules are at the beginning of the program, followed by the bookkeeping rules (those responsible for updating the current parental and subgoals), followed by the initializing "split" rules, followed by the rules for action at each stroke of the cycle. The "split" rules were made necessary because the condition portion of a rule in ART does not have a provision to match on two OR'ed schema slots.

#### Program Outline

The engine state is modeled by a schema named CURRENT which is modified by the action of the stroke and ignition rules to reflect the operation of the engine. Each relevant component of the engine state is stored in a slot of the schema. At the same time, each slot in CURRENT is compared to a similar slot of the IDEAL engine state. Discrepancies, such as the spark plug not firing, cause error flags to be set which allow the diagnostic rules to fire. In this case, each flag triggers one diagnosis, but combinations of flags could also do this.

Diagnostic rules printout specific error messages and take corrective action (replacing the spark plug). They also query if an explanation is required. If one is, another flag is set.

The combination of the error and explanation flags allow the firing of explanation rules, of which there are two in this program.

### Conclusions

The program served as a learning process, but ended up with serious deficiencies:

The fault tree was never more than two levels deep (both spark plugs fail) and did not demonstrate any combinatorial failures nor did it ever have to "guess". There couldn't be a wrong diagnosis.

All explanations were developed as the program "sequenced" through the simulation. No explanations could be given after the cycle continued: the program has no memory of what has already happened; it can only respond to the current state. This could be remedied by time-stamping all facts (saving the telemetry stream), but this would also require a new set of rules to react with past data in addition to those already existing which react with current data, effectively doubling the size of the program (at least).

All explanations either exist from the beginning or they could not be given. The drawback with programming in this style is that all possible faults and fault combinations must be figured in advance and coded into the program. This is trivial for a program this size, but is not practical for a large program. This increases the size of the program exponentially with the number of components. It also requires being able to simulate the "correct" functioning of the system at all times in order to detect discrepancies.

The source code for this program is shown in Appendix A.

### Proposed Further Avenues of Exploration

The concept employed with this program would only allow explanations to be given "on the fly", that is, only after each diagnosis and/or fault correction. Explanation cannot be generated past that point in time; there is no memory of the transaction.

To avoid this fault then in order to generate explanations of past events either:

1. Save all explanations for possible future recall, or;
2. It must be possible to generate explanations from saved data.

There are a number of unexplored avenues here, such as the optimum way of generating explanations, the best way of storing data, etc.

Another concept to be explored is that of partitioning the expert system. The program, as currently written, does not support this, but the idea of breaking the system into modules, either functionally, where a module would perform certain tasks, or by domain, where each module would service a system or subsystem of the overall domain. The ability to do so would have quite an effect on the memory requirements and speed of the system.

#### D. Ada Implementation of a C&T Subsystem Simulator (TRW), Fault Detection and Explanation Facility with User Interaction

##### Motivation (objective)

This demonstration program was initiated for two reasons. First to demonstrate how a sequential software system could effectively duplicate the results of a simulation written in C and an expert system written in a specialized rule-based language such as ART (Automated Reasoning Tool by Inference Corp.). The second reason was to demonstrate that in contrast to conventional rule-based systems a sequential system can more easily store facts in a database and access them for an explanation facility. An ancillary reason was to examine how modularization could be used when implementing both diagnostic and explanation facilities.

##### Structure (program outline)

The program, written in Ada, consists of five modules called packages.

###### 1. MAIN\_SIM\_MOD3

This is really not a module but rather the driver program for the demonstration system. It essentially structures the system by calling subprograms. A simplified algorithm for this program is given in the following enumerated steps.

- (1) Initialize the communications system database;
- (2) Check for inconsistencies in the data, and if there are any, call a subprogram to ask the human monitor to correct the data;
- (3) Call the equipment emulator program;
- (4) Based upon the measured equipment output and the status of the switches, determine the condition of the equipment (i.e., diagnose the probable cause of failure, if any);
- (5) Call a subprogram to display the status of the equipment to the human monitor;
- (6) Call subprograms to provide an explanation of the diagnosis if requested;
- (7) Call a subprogram to interact with the human monitor to see if another simulation is to be run;
- (8) If the human monitor wishes to stop the program then terminate else call a subprogram to ask the monitor to update the simulation parameters and then go to step (2).

2. Y OUT MOD

This package contains the equipment emulator subprogram. It effectively simulates the action of the hardware given the parameters in the equipment status database.

3. FAULT-ANALYZE

This package contains the subprograms which measure the observable parameters and determines the probable fault, if any.

4. EXPLAIN DIAGNOSIS

This package presents an analysis of the reasons behind the fault diagnosis when requested by the human monitor.

5. I O SIM MOD

This package is the one which accesses and updates the simulated equipment parameters.

The source code for this system is shown in Appendix B.

#### Observations Based Upon Results

Not too much can be asserted with certainty but there are a few points which the work suggests. Among those are:

1. To explain even a moderately complex fault analysis decision it may be simpler to parallel a part of the decision process rather than try to filter the information from information written into the data base. Again, a trade-off exists between the classical performance parameters of execution time versus memory (primary and secondary storage). For example, in the diagnostic package called FAULT\_ANALYZE the principal program DIAGNOSIS tests the output power EQUIP\_Y\_OUT\_LEVEL and if it is less than -145 dbm it calls a "low level" program to examine the on-off switches in SWITCH\_STATUS. If the main power switch is "ON" then the oscillator switches are tested. If the selected oscillator is "ON" then the program "reasons" that the selected oscillator is inoperative. Now when an explanation of this event is requested the EXPLAIN\_DIAGNOSIS package is activated. Examining the code for procedure EXPLAIN\_DIAGNOSIS we see that it parallels the reasoning of procedures DIAGNOSIS and SWITCH\_STATUS in package FAULT\_ANALYZE, that is to say, it has the same nested "if" structure. The only thing it adds is the diagnostic message, "We found the selected oscillator switch to be ON, the power output was in the noise level, so potentially we had a catastrophic oscillator failure." If the DIAGNOSIS and SWITCH\_STATUS programs had been more cooperative they could have selected the appropriate literal value for an enumeration variable and stored this "hook" in the data base for access by the EXPLAIN\_DIAGNOSIS package. Then all the EXPLAIN\_DIAGNOSIS procedure would have to do is examine this variable by virtue of a simple "case" statement and supply the quoted explanation, "We found..etc."

Such a "type" definition for the desired variable might be:

```
type Switch_Permutation_Type is
  (POWER_OFF,
   POWER_ON_OSC_OFF,
   POWER_ON_OSC_ON);
```

A variable of this type could be set equal to one of the enumeration literals by procedure SWITCH\_STATUS in package FAULT\_ANALYZE.

2. Communicating with a user and writing facts to files and/or ephemeral data storage which facts are useful for explanation facilities may require interfacing a given expert system to procedural language I/O routines.
3. It seems that it should be possible to modularize a given expert system to some extent. For example, a FAULT\_ANALYZE subsystem could in large measure be separate from an EXPLAIN\_DIAGNOSIS subsystem. There would probably be some shared data and possibly even some shared utility routines, but the main thread of each subsystem could be separate.
4. One of the deficiencies of this implementation is that explanations are done with the same database as the fault analysis system, and before any recovery corrections are made. Thus, the database is unchanged when the explanations are made. The programming system could easily be altered to allow changes in the data and still allow an explanation after the fact. The technique employed would be to create two variables for each entity, one for the old value and one for the current value. This is easily done in Ada or in any procedural language but is more difficult in a so-called expert systems language. This may indicate that any production system would require its expert systems language to provide an interface to procedural language subprograms.

#### Future Direction

The next task which may be proposed is to expand this demonstration program to include more realistic fault detection with more realistic "hook" data generation. Then the explanation subsystem could be restructured to use these improvements. A parallel system in ART will also be implemented (if feasible).

SUMMARY OF OVERALL RESULTS AND RECOMMENDATIONS

- A. The issue of storing the complete decision tree versus only storing the knowledge base for an explanation facility has not been resolved, but a few alternatives to be explored have been identified.
  - 1. Store the decision tree in its entirety with perhaps one branch node for paths not taken at each node in the decision tree.
  - 2. Build and store a complete knowledge data base whenever an anomaly occurs. (This could be any undesirable outcome such as the software system displaying unanticipated behavior. This could be signalled by the astronaut monitor or the expert system itself such as when a system failure is detected by the low level systems.)
  - 3. Store only the facts with appropriate time stamps, and when an explanation is required, load a system containing rules similar to the original expert system so as to effectively parallel the operation of the original expert system but this time allowing the user to interrupt this parallel system to ask for appropriate explanations about paths not taken.

These alternatives are not mutually exclusive but all should be examined in future work.

- B. The issue of the features of an expert systems language which language is appropriate for development and perhaps implementation of software systems which meet C & T functional requirements needs to be addressed. This recommendation is based upon the experience acquired by the structuring of a simple simulation and diagnostic-explanation program written in ART, (DIAG4.ART in Appendix A), the program had to be all in one module. In addition, there were the file I/O deficiencies of ART and the difficulty of storing more than one value for a given parameter. As a minimum any such language should be capable of interfacing with a compiler language program in a straightforward manner.
- C. It is recommended that the issues of object-oriented design for expert systems be raised and investigated. In addition, the concept of supplying adequate "hooks" for explanation should be addressed early. Explanation facilities are best implemented when they are built in and not just "added" as a separate entity. If this is not done the explanation facility requires additional resources and must parallel some previously "paths" already trodden by other systems. The issues of object-oriented design, modularization, and so-called information hiding may not be just academic but a necessity for implementation of any large and perhaps distributed control and monitoring system, be it a procedural and/or rule-based software system. The topic of object-oriented design for expert systems addressing anomaly detection, recovery and explanation was examined by structuring a procedural software system in Ada. The system consisted of a driver and hardware status simulator, fault diagnosis, and fault explanation modules for a small radio frequency communication subsystem. Implementing expert system functions in Ada indicated that modularization and object-oriented design indeed are feasible without compromising effectiveness.

**APPENDIX A**

**Source Code for DIAG4.ART**

**an Engine Diagnostic/Explanation Program**

```

;;; -- Mode: ART; Base: 10.; Package: ART-User --
(defschema engine-state "state of engine - beginning of intake-stroke"
  (carburation good)
  (piston-direction descending)
  (sparkplug1 good)
  (sparkplug2 standby))

(defschema current
  (instance-of engine-state))

(defschema ideal
  (instance-of engine-state))

(deffacts state
  (state-name intake))

(defrule compare-ok "compares current and ideal if same"
  (schema current (carburation ?state3))
  (schema ideal   (carburation ?state3))
  (schema current (piston-direction ?state4))
  (schema ideal   (piston-direction ?state4)))
=>
  (printout t t "compared ok" t t)

(defrule compare-not-carburation
  (schema current (carburation ?state3))
  (schema ideal   (carburation ~?state3)))
=>
  (printout t t "carburation compared not ok" t t)
  (assert (error-trap carburation))

(defrule compare-not-direction
  (schema current (piston-direction ?state4))
  (schema ideal   (piston-direction ~?state4)))
=>
  (printout t t "piston-direction compared not ok" t t)
  (assert (error-trap direction))

(defrule no-ignition
  (state-name power)
  ?ignition <- (ignition fail)
=>
  (printout t t "sparkplug did not fire" t t)
  (printout t t ?ignition t t)
  (assert (error-trap ignition))
  (retract ?ignition))

(defrule intake-stroke
  ?state-name <- (state-name intake)
  (schema current (carburation ?state3))
  (schema ideal   (carburation ?state3))
  (schema current (piston-direction ?state4))
  (schema ideal   (piston-direction ?state4)))
=>
  (printout t t "1st Stroke - Intake Completed" t t)
  (modify
    (schema current
      (piston-direction ascending)))
  (modify
    (schema ideal
      (piston-direction ascending)))
  (retract ?state-name)
  (assert (state-name compression)))

(defrule compression-stroke
  ?state-name <- (state-name compression)
  (schema current (carburation ?state3))
  (schema ideal   (carburation ?state3))
  (schema current (piston-direction ?state4))
  (schema ideal   (piston-direction ?state4)))
=>
  (printout t t "2nd Stroke - Compression" t t)
  (modify
    (schema current
      (piston-direction descending)))
  (modify
    (schema ideal
      (piston-direction descending)))
  (retract ?state-name)
  (assert (state-name exhaust)))

```

ORIGINAL PAGE IS  
OF POOR QUALITY

```

        (schema ideal
            (piston-direction descending)))
    (retract ?state-name)
    (assert (state-name power)))
;   (printout t t "Did sparkplug : fire or fail?" t t)
;   (assert (ignition =(read)))))

(defrule power-stroke
    ?state-name <- (state-name power)
    ?ignition <- (ignition fire)
    (schema current (carburation ?state3))
    (schema ideal (carburation ?state3))
    (schema current (piston-direction ?state4))
    (schema ideal (piston-direction ?state4))
=>
    (printout t t "3rd Stroke - Power" t t)
    (modify
        (schema current
            (piston-direction ascending)))
    (modify
        (schema ideal
            (piston-direction ascending)))
    (retract ?state-name)
    (assert (state-name exhaust))
    (retract ?ignition))

(defrule exhaust-stroke
    ?state-name <- (state-name exhaust)
    (schema current (carburation ?state3))
    (schema ideal (carburation ?state3))
    (schema current (piston-direction ?state4))
    (schema ideal (piston-direction ?state4))
=>
    (printout t t "4th Stroke - Exhaust" t t)
    (modify
        (schema current
            (piston-direction descending)))
    (modify
        (schema ideal
            (piston-direction descending)))
    (retract ?state-name)
    (assert (state-name intake)))

(defrule switch-plugs
    ?error-flag <- (error-trap ignition)
    ?state-name <- (state-name ?name)
    (schema current (sparkplug2 standby))
=>
    (modify
        (schema current
            (sparkplug1 fail)
            (sparkplug2 good)))
;   (retract ?error-flag)
    (retract ?state-name)
    (assert (state-name compression))
    (printout t t "Sparkplug1 set to Failed" t t)
    (printout t t "Sparkplug2 reset from standby to good" t t)
    (printout t t "Is an explanation desired? yes or no" t t)
    (assert (explanation-flag =(read)))))

(defrule no-plugs
    ?error-flag <- (error-trap ignition)
    ?state-name <- (state-name ?name)
    (schema current (sparkplug2 good))
    (schema current (sparkplug1 fail))
=>
    (modify
        (schema current
            (sparkplug2 fail)))
;   (retract ?error-flag)
    (retract ?name)
    (assert (state-name compression))
    (printout t t "Sparkplug2 set to Failed" t t)
    (printout t t "Is an explanation desired? yes or no" t t)
    (assert (explanation-flag =(read))))

```

```
(defrule ignition-fire
  (state-name power)
  (split ((sparkplug1 current good)
          =>
          ((sparkplug2 current good)
           =>)))
  =>
  (printout t t "Did sparkplug : fire or fail?" t t)
  (assert (ignition =(read)))))

(defrule explanation-1
  ?error-flag <- (error-trap ignition)
  ; ?ignition <- (ignition ?fire)
  (schema current (sparkplug1 fail))
  (schema current (sparkplug2 good))
  ?expl-flag <- (explanation-flag yes)
  =>
  (printout t t "Sparkplug 1 did not fire. Therefore it was replaced by the backup." t t)
  (retract ?error-flag)
  (retract ?expl-flag))

(defrule explanation-2
  ?error-flag <- (error-trap ignition)
  ; ?ignition <- (ignition ?fire)
  (schema current (sparkplug1 fail))
  (schema current (sparkplug2 fail))
  ?expl-flag <- (explanation-flag yes)
  =>
  (printout t t "Sparkplug 2 did not fire.
Since it is the backup sparkplug,
(sparkplug 1 has already been considered failed)
there is no remedy.
However, since it is unusual to have both sparkplugs
failed, the problem may reside elsewhere." t t)
  (retract ?error-flag)
  (retract ?expl-flag))
```

**APPENDIX B**

**Source Code for System MAIN\_SIM\_MOD3.ADA**

**a Communication Amplifier Diagnostic/Explanation Software System**

TYP\_DEF\_SIM VAX Ada V1.3-23  
USER2:[TFL.ADADIR]TYP\_DEF\_SIM\_ADA;2 Page 1  
17-Nov-1986 15:34:32  
17-Nov-1986 15:34:04

```
package TYP_DEF_SIM is
```

**type** SWITCH is (ON, OFF);

**type FAULT is (ACTIVE, INACTIVE);**

```
-12 type SOURCE is (A,B);
```

**type** CONTINUE is (YES,NO);

**D TYP DEF SIM;**

Name      ID#      City      State

TYP DEF SIN : SCODE

55 TYP\_DEF\_SIM : SCALAR  
12 TYP\_DEF\_SIM : CONSTANT

%ADAC-I-CL-ADDED, Package specification TYP DEF SIM added to library  
%Replaces older version compiled 17-Nov-1986\_00:53

## **PORTABILITY SUMMARY**

shows no uses of potentially non-portable constructs



```

58
59           |   |   |   {   |   -J\ard 7 24| 28 {   X A|  .3-|  _SIM |  _SIM _MOD3 .ADA;3
60           |   |   |   {   |   18-Jan-1987 22:31:20  USER2:[TFL.ADA DIR]MAIN _SIM _MOD3 .ADA;3
61           |   |   |   {   |   (1)
62
63
64
65
66
67
68
69
70
71
72
73
74
75
76
77
78
79
80
81
82
83
84
85
86
87
88
89
90
91
92
93
94
95
96
97
98
99
100
101
102
103
104
105
106
107
108
109
110
111
112
113

-- 6. Write out the equipment status to the CRT (procedure OUT_PARAMS
-- in package I_O_SIM_MOD).

-- 7. Interactively ask the monitor whether an explanation of the diagnosis
-- is desired. If so then supply same.

-- 8. Interactively ask the monitor if the simulation is to be continued.

-- 9. If the monitor chooses not to continue then exit.

-- 10. If the choice is to run another simulation the ask what parameters
-- are to be changed (i.e. call NEW_PARAMS in package I_O_SIM_MOD).

-- 11. Go back to item 2.

-- end algorithm MAIN_SIM_MOD

with TYP DEF_SIM; with Y_OUT_MOD; with I_O_SIM_MOD; with FAULT_ANALYZE;
with EXPLAIN_DIAGNOSIS;
use TYP_DEF_SIM; use Y_OUT_MOD;

Procedure MAIN_SIM_MOD3 is

  AGAIN : CONTINUE:= YES;
  EXPLAIN : CONTINUE:= YES;
  EQPT_Y,
  FREQ_SRC_A,
  FREQ_SRC_B : SWITCH;
  REF_FREQ_LEVEL_A,
  REF_FREQ_LEVEL_B : FLOAT;
  EQPT_Y_OUT_LEVEL_FAIL : FAULT ;
  EQUIP_Y_OUT_LEVEL,
  EQUIP_Y_OUT_LEVEL_SIM,
  EQUIP_X_OUT_LEVEL : FLOAT;

begin

  I_O_SIM_MOD.I_O_INIT(EQPT_Y,FREQ_SRC_A,FREQ_SRC_B,EQPT_Y_OUT_LEVEL_FAIL,
    REF_FREQ_LEVEL_A,REF_FREQ_LEVEL_B);

  EQUIP_Y_OUT_LEVEL_SIM,EQUIP_X_OUT_LEVEL);

  while AGAIN = YES
    loop

      if FREQ_SRC_A=ON and FREQ_SRC_B=ON
        then I_O_SIM_MOD.I_O_SWITCH(FREQ_SRC_A,FREQ_SRC_B);
      end if; -- If both "ON" force a choice between A or B "ON"
      I_O_SIM_MOD.NEMPAGE;

```

```

01      SIM| 3 | 1 | 1 | 1 | 1 | -Jaq| 7 27 | X A| 1.3| MAIN_SIM_MOD3.ADA;3 (1)

```

```

114 EQUIPMENT_Y_O(EQPT_Y,FREQ_SRC_A,FREQ_SRC_B,
115     REF_FREQ_LEVEL_A,REF_FREQ_LEVEL_B,EQPT_Y_OUT_LEVEL_FAIL,
116     EQUIP_X_OUT_LEVEL,EQUIP_Y_OUT_LEVEL_SIM,
117     EQUIP_Y_OUT_LEVEL);-- Run the Simulator
118
119 FAULT_ANALYZE.DIAGNOSIS(EQPT_Y,FREQ_SRC_A,FREQ_SRC_B,
120     EQUIP_Y_OUT_LEVEL_SIM,
121     EQUIP_Y_OUT_LEVEL,EQUIP_X_OUT_LEVEL);-- Diagnose fault
122
123 I_O_SIM_MOD.OUT_PARAMS(EQPT_Y,FREQ_SRC_A,FREQ_SRC_B,EQPT_Y_OUT_LEVEL_FAIL,
124     REF_FREQ_LEVEL_A,REF_FREQ_LEVEL_B,
125     EQUIP_Y_OUT_LEVEL_SIM,EQUIP_X_OUT_LEVEL,EQUIP_X_OUT_LEVEL);
126
127 I_O_SIM_MOD.QUERY_EXPLAIN(EXPLAIN);-- Does monitor want an explanation
128
129 if EXPLAIN =YES
130 then
131     EXPLAIN_DIAGNOSIS.EXPLAIN_DIAGNOSIS(EQPT_Y,FREQ_SRC_A,FREQ_SRC_B,REF_FREQ_LEVEL_A,REF_FREQ_LEVEL_B,
132         EQUIP_Y_OUT_LEVEL,EQUIP_X_OUT_LEVEL,
133         EQUIP_Y_OUT_LEVEL_EXPLAIN);-- If explanation desired
134 end if;
135
136 I_O_SIM_MOD.AGAIN_I_O(AGAIN);-- Ask human if wants to repeat simulation
137
138 exit when AGAIN = NO;
139
140 I_O_SIM_MOD.NEW_PARAMS(EQPT_Y,FREQ_SRC_A,FREQ_SRC_B,EQPT_Y_OUT_LEVEL_FAIL,
141     REF_FREQ_LEVEL_A,REF_FREQ_LEVEL_B,
142     EQUIP_Y_OUT_LEVEL_SIM,EQUIP_X_OUT_LEVEL);
143
144 end loop;
145
146 end MAIN_SIM_MOD3;

```

#### PSECT MAP

Psect	Hex Size	Dec Size	Name
0	0000001F3	499	MAIN_SIM_MOD3.\$CODE

%ADAC-I-CL\_ADDED, procedure body MAIN\_SIM\_MOD3 added to library

#### PORTABILITY SUMMARY

There are no uses of potentially non-portable constructs

#### LIBRARY SUMMARY

USER2:[TFL.ADADIR.ADALIB]

Unit name	Nodes	Percent read	Blocks	read	Unit kind
-----------	-------	--------------	--------	------	-----------





```

58
59
60      procedure FAULT_MSG_LIST(MESSAGE_NO : in INTEGER) is
61          -- Test all on/off switch stati, then decide upon
62          -- what diagnosis to transmit to equipment monitor
63
64      MESSAGE_NO is
65
66      when 1 =>
67          NEW_LINE;PUT(" Equipment output power is down in the noise level."); -- i.e -125 dbm
68
69          begin -- what diagnosis to transmit to equipment monitor
70
71          case MESSAGE_NO is
72
73              when 2 =>
74                  NEW_LINE;PUT(" The main switch is 'ON' so an internal failure occurred");
75
76                  NEW_LINE;PUT(" Both oscillators A and B are OFF so no wonder !");
77
78                  NEW_LINE;PUT(" Next pass try turning on either oscillator.");
79
80                  NEW_LINE;PUT("The selected oscillator may have completely failed");
81
82                  NEW_LINE;PUT(" Next pass try turning on the other oscillator");
83
84
85                  when 4 =>
86                      NEW_LINE;PUT("The Main switch is 'OFF' so no wonder the output is noise");
87
88
89                  when 6 =>
90                      NEW_LINE;PUT("The OPERATIONAL DIAGNOSIS is");
91
92                      NEW_LINE;PUT("Since the Power output is ");
93
94
95
96
97
98
99
100
101
102
103
104
105
106
107
108
109
110
111
112
113
114

```

```

115      IN_          |   -Jan-7 09:34 |  IX A| 1.3--^
116      | 20-Jan-1987 00:51:15 | USER2!TFL.ADADR!I O_SIN_MOL.AUA;19[ (1)
117
118      procedure QUERY_EXPLAIN( EXPLAIN : out CONTINUE ) is
119      begin -- This communicates with the human monitor asking if an
120      -- explanation desired
121      PUT( " Do you want to know the reasoning behind the diagnostic decision? ( YES/NO ) ";
122      AGAIN_IO.GET(EXPLAIN);NEW_LINE(2);
123
124      end QUERY_EXPLAIN;
125
126      procedure EXPLAIN_MSG_LIST(MESSAGE_NO : in INTEGER) is
127
128      begin -- This procedure contains some of the diagnostic logic
129      -- for analyzing a substandard power output
130
131      case MESSAGE_NO is
132
133      when 10 =>
134      NEW_LINE;PUT(" The OPERATIONAL DIAGNOSIS EXPLANATION is:");  

135      NEW_LINE;
136      NEW_LINE;PUT(" The output measured was very low and noisy");
137      NEW_LINE;
138
139      when 11 =>
140      NEW_LINE;PUT(" The output measured was very low and noisy");
141      NEW_LINE;PUT(" yet the master switch was 'ON' ");
142      NEW_LINE;PUT(" so the failure was something else.");
143
144      when 12 =>
145      NEW_LINE;PUT( " We then found that both the oscillator switches were 'OFF' ");
146      NEW_LINE;PUT( " We found the selected oscillator switch to be 'ON' ");
147      NEW_LINE;PUT( " so the malfunction was a set-up error." );
148
149      when 13 =>
150
151      NEW_LINE;PUT(" The output was between -145.0 dbm and -90.0 dbm. Thus the output");
152      NEW_LINE;PUT(" device was probably OK but the oscillator was below threshold.");
153      NEW_LINE;PUT(" The oscillator output was insufficient to drive the output device.");
154      NEW_LINE;PUT(" The logical action is to select the other oscillator on the next pass.");
155
156      when 14 =>
157
158      NEW_LINE;PUT(" The output was between -145.0 dbm and -90.0 dbm. Thus the output");
159      NEW_LINE;PUT(" device was probably OK but the oscillator was below threshold.");
160      NEW_LINE;PUT(" The oscillator output was insufficient to drive the output device.");
161      NEW_LINE;
162
163      when 15 =>
164
165      NEW_LINE;PUT(" The output was between -145.0 dbm and -90.0 dbm. Thus the output");
166      NEW_LINE;PUT(" device was probably OK but the oscillator was below threshold.");
167      NEW_LINE;PUT(" The oscillator output was insufficient to drive the output device.");
168      NEW_LINE;PUT(" The logical action is to select the other oscillator on the next pass.");
169
170

```

```

01_O_SIM_MOD          Page 4
20-Jan-1987 00:51:34 VAX Ada V1.3-23
USER2:[TFL.ADADIR]O_SIM_MOD.ADA;19 (1)

when 16 =>
  NEW_LINE;PUT( " A degradation of output had occurred; however the output was above-90.0 dbm");
  NEW_LINE;PUT( " but this is the output when output device failure occurs." );
  NEW_LINE;PUT( " This indicates that the selected oscillator was probably OK" );
  NEW_LINE;PUT( " since there was some signal leaking through the circuitry." );
  NEW_LINE;PUT( " but there was probably an output device failure." );
  NEW_LINE;

when 17 =>
  NEW_LINE;PUT( " Normal operation with normal output has occurred." );

when others =>
  NEW_LINE; PUT( " ERROR in EXPLAIN_DIAGNOSIS with MESSAGE_NO. " );
  NEW_LINE;
  end case;

end EXPLAIN_MSG_LIST;

procedure OUT_PARAMS(EQPT_Y, FREQ_SRC_A,FREQ_SRC_B : in SWITCH;-- Equipment sw's
                     EQPT_Y_OUT_LEVEL_FAIL : in FAULT; -- HW failure
                     REF_FREQ_LEVEL_A, REF_FREQ_LEVEL_B, -- Osc Output
                     EQUIP_Y_OUT_LEVEL_SIM, -- HW failure output level
                     EQUIP_X_OUT_LEVEL, -- Normal Output Power
                     EQUIP_Y_OUT_LEVEL : in FLOAT) is
begin -- This procedure outputs the status of all simulation variable
      -- database for the current pass of the simulator code
  NEW_LINE;
  PUT("The Status of the system is :");NEW_LINE(2);
  PUT("Equipment Switch is ");SWC_ENUM_IO.PUT(EQPT_Y);NEW LINE;
  PUT("Frequency Source A is ");SWC_ENUM_IO.PUT(FREQ_SRC_A);-- Switches
  PUT("Frequency Source B is ");SWC_ENUM_IO.PUT(FREQ_SRC_B);NEW LINE;
  PUT("The actual Power output of the system is ");PARAM_IO.PUT(EQUIP_Y_OUT_LEVEL);NEW LINE;
  NEW LINE(2);
  PUT("The status of the equipment and simulator data is: ");
  NEW_LINE;PUT(" (these data normally unavailable to observer)" );
  NEW_LINE(2);
  PUT("The GREMLIN is ");FAULT_ENUM_IO.PUT(EQPT_Y_OUT_LEVEL_FAIL);NEW LINE;
  PUT("The GREMLIN, if active causes_system output of "); -- power_lpower levels
  PARAM_IO.PUT(EQPT_Y_OUT_LEVEL_SIM);
  NEW LINE;
  PUT("The oscillator A normal output is ");PARAM_IO.PUT(REF_FREQ_LEVEL_A);
  NEW LINE;
  PUT("The oscillator B normal output is ");PARAM_IO.PUT(REF_FREQ_LEVEL_B);
  NEW LINE;
  PUT("The normal system output is ");PARAM_IO.PUT(EQUIP_X_OUT_LEVEL);
  NEW LINE(2);
  end OUT_PARAMS;

```

```

228 procedure PARAM_OUT(PWR_LEVEL : in FLOAT) is
229 begin
230   PARAM_IO.PUT(PWR_LEVEL);
231 end PARAM_OUT;
232
233
234
235 procedure AGAIN_I_O(AGAIN: out CONTINUE) is
236 begin
237   -- Ask the equipment monitor whether or not to continue
238   NEW_LINE;
239   PUT(" Do you wish to change some parameters and try again ? ");
240   PUT(" (type in YES/NO) "); AGAIN_IO.GET(AGAIN); SKIP_LINE;
241   NEW_LINE(2);
242 end AGAIN_I_O;
243
244 procedure NEW_PARAMS(EQPT_Y, FREQ_SRC_A, FREQ_SRC_B : in out SWITCH;-- Equipment SW's
245   EQPT_Y_OUT_LEVEL_FAIL : in out FAULT; -- HW failure
246   REF_FREQ_LEVEL_A, REF_FREQ_LEVEL_B, -- Osc output
247   EQUIP_Y_OUT_LEVEL_SIM, -- HW failure output level
248   EQUIP_X_OUT_LEVEL : in out FLOAT) is -- Normal out
249   NEW_LINE(2);
250
251 SubTYPE INPUT_STRING is STRING(1..9);
252 STRLEN : NATURAL; -- Length of the string read from the keyboard buffer
253 LOCAL_STRING: INPUT_STRING; -- Declaration of max length to be read
254 CONVLEN : POSITIVE; -- Dummy local var containing len of enum attrib
255
256 begin -- Display present parameter values and solicit new ones
257   PUT("Enter new values and <CR> or just <CR> to let value stand as is");NEW_LINE(2);
258
259   -- Show master switch position (ON/OFF) and ask for new value
260
261   PUT("Equipment switch is ");SWC_ENUM_IO.PUT(EQPT_Y);NEW_LINE;
262   PUT("Enter new value (ON/OFF) ");
263   GET_LINE(LOCAL_STRING,STRLEN); -- Get new input
264   if STRLEN /= INPUT_STRING'FIRST-1 -- if an input (i.e. not just a <CR>)
265   then SWC_ENUM_IO.GET(LOCAL_STRING,EQPT_Y,CONVLEN); -- then enter into DBMS
266   end if; LOCAL_STRING := " ";NEW_LINE; -- reinitialize string object
267
268   -- Show frequency sources switch positions and ask for new values
269
270   PUT("Freq source A is ");SWC_ENUM_IO.PUT(FREQ_SRC_A);NEW_LINE;
271   PUT("Enter new value (ON/OFF) ");GET_LINE(LOCAL_STRING,STRLEN);
272   if STRLEN /= INPUT_STRING'FIRST-1 -- if an input then get it as a string
273   then SWC_ENUM_IO.GET(LOCAL_STRING,FREQ_SRC_A,CONVLEN); -- convert string to its enumeration type
274   end if; LOCAL_STRING := " ";NEW_LINE;
275   PUT("Freq source B is ");SWC_ENUM_IO.PUT(FREQ_SRC_B);NEW_LINE;
276   PUT("Enter new value (ON/OFF) ");GET_LINE(LOCAL_STRING,STRLEN);
277   if STRLEN /= INPUT_STRING'FIRST-1
278   then SWC_ENUM_IO.GET(LOCAL_STRING,FREQ_SRC_B,CONVLEN);
279   end if; LOCAL_STRING := " ";NEW_LINE;
280
281   -- Present the simulated failure status (ACTIVE/INACTIVE) ask which?
282
283   PUT("The GREMLIN is ");FAULT_ENUM_IO.PUT(EQPT_Y_OUT_LEVEL_FAIL);
284   NEW_LINE;
285

```

```

;IN] | | | | | | | -Jaf| 7 0{ 34 | AX A| 1.3-| (1)
| 20-Jan-1987 00:51:15 | USER2:[TFL-ADADIR]I_O_SIM_MOD.ADA;19 | q

PUT( " Enter new value (ACTIVE/INACTIVE) " );GET_LINE(LOCAL_STRING,STRLEN);

if STRLEN /= INPUT_STRING'FIRST-1
then FAULT_ENUM_IO.GET(LOCAL_STRING,EQPT_Y_OUT_LEVEL_FAIL,CONVLEN);
end if; LOCAL_STRING := " ";NEW_LINE;

-- Present the output power levels for each oscillator and ask for updates

92 PUT("The Oscillator A output is ");PARAM_IO.PUT(REF_FREQ_LEVEL_A);
93 NEW_LINE;
94 PUT(" Enter a new value for Oscillator A Power output in dbm " );NEW_LINE;
95 PUT(" (must be > -145.0 ) "); GET_LINE(LOCAL_STRING,STRLEN);
96 if STRLEN /= INPUT_STRING'FIRST-1
97 then PARAM_IO.GET(LOCAL_STRING,EQPT_Y_OUT_LEVEL_A,CONVLEN);
98 end if; LOCAL_STRING := " ";NEW_LINE;
99 PUT("The Oscillator B output is ");PARAM_IO.PUT(REF_FREQ_LEVEL_B);
00 NEW_LINE;
01 PUT(" Enter a new value for oscillator B Power output in dbm " );NEW_LINE;
02 PUT(" ( must be > -145.0 ) "; GET_LINE(LOCAL_STRING,STRLEN);
03 if STRLEN /= INPUT_STRING'FIRST-1
04 then PARAM_IO.GET(LOCAL_STRING,EQPT_Y_OUT_LEVEL_B,CONVLEN);
05 end if; LOCAL_STRING := " ";NEW_LINE;
06
07 -- Present the normal operation power and ask for parameter change
08
09 PUT("The normal system power output is ");PARAM_IO.PUT(EQUIP_X_OUT_LEVEL);
10 NEW_LINE;
11 PUT(" Enter a new value for system power output if desired, " );
12 GET_LINE(LOCAL_STRING,STRLEN);
13 if STRLEN /= INPUT_STRING'FIRST-1
14 then PARAM_IO.GET(LOCAL_STRING,EQUIP_X_OUT_LEVEL,CONVLEN);
15 end if; LOCAL_STRING := " ";NEW_LINE;
16
17 -- Present the output power level when an output device fails (dbm) and inquire
18
19 PUT("The output power when output device has failed," );NEW_LINE;
20 PUT(" i.e. ACTIVE GREMLIN is "); PARAM_IO.PUT(EQUIP_Y_OUT_LEVEL_SIM);
21 NEW_LINE;
22 PUT(" Enter a new value for this 'GREMLIN' power out if desired, " );
23 NEW_LINE;PUT("note that it must be less than normal power out,");
24 NEW_LINE;PUT(" but must also be > -90.0 ");GET_LINE(LOCAL_STRING,STRLEN);
25 if STRLEN /= INPUT_STRING'FIRST-1
26 then PARAM_IO.GET(LOCAL_STRING,EQUIP_Y_OUT_LEVEL_SIM,CONVLEN);
27 end if; LOCAL_STRING := " ";NEW_LINE(2);
28
29 -- Ready to loop back and do it again
30
31 PUT_LINE(" Ready or not; Here we go again !! " );
32 NEW_LINE;
33 end NEW_PARAMS;
34
35 end I_O_SIM_MOD;

```

ORIGINAL PAGE IS  
OF POOR QUALITY

Psect	Hex	Size	Dec	Size	Name
					Y_OUT_MOD_CODE
0	00000037		55		
1	00000000		1		Y_OUT_MOD_CODE
2	00000000		1		Y_OUT_MOD_CODE

%ADAC-I-CL<sub>1</sub> ADDED, Package specification Y OUT MOD added to library  
2011-11-27 14:14:15 UTC Version controlled 27-Nov-1986 00:15

卷之三

卷之三

**RADAC-I-CL ADDED**, Package body Y OUT MOD added to library  
Corresponds to package specification Y OUT MOD compiled 27-Nov-1986 00:25

REF ID: A12345

Name	Dec	Size	Hex	Size	sect
FAULT_ANALYZE_SCODE	32		0	00000020	0
FAULT_ANALYZE_SCONSTANT	12		1	0000000C	1

**ADAC-I-CL\_ADDED**, Package specification FAULT ANALYZE added to library  
Replaces older version compiled 18-Jan-1987 21:21

卷之三

卷之三

תורת היחסים

Unit name	Nodes	Percent read	Blocks	read	Package specification package specification
TYP_DEF_SIM	7	41	7	7	
CNT_WD	7	7	5	5	
WDT	7	7	5	5	
WDT_CNT	7	7	5	5	

```

19
20 package body FAULT_ANALYZE is
21
22   MESSAGE_NO : INTEGER;
23
24   procedure SWITCH_STATUS(EQPT_Y,FREQ_SRC_A,FREQ_SRC_B : in SWITCH) is
25
26     -- Called by MAIN SIM
27     -- Test all on/off switch stati, then decide upon
28     begin -- what diagnosis to transmit to equipment monitor
29
30     MESSAGE_NO := 1; -- PUT(" Equipment output Power is down in the noise level.");
31
32     if EQPT_Y = ON
33
34     then
35       MESSAGE_NO := 2; -- Main switch is on so must be other failure
36       I_O_SIM_MODFAULT_MSG_LIST(MESSAGE_NO);
37       if (FREQ_SRC_A=OFF) and (FREQ_SRC_B=OFF)
38
39       then
40         MESSAGE_NO := 3;
41         -- PUT(" Both oscillators A and B are OFF so no wonder !!!");
42         -- PUT(" Next pass try turning on either oscillator.");
43
44       else
45         MESSAGE_NO := 4; -- Selected oscillator must Bbe inoperative so
46         I_O_SIM_MODFAULT_MSG_LIST(MESSAGE_NO);
47
48       else
49         MESSAGE_NO := 5; -- Main Switch is 'OFF' that explains the poor output
50         I_O_SIM_MODFAULT_MSG_LIST(MESSAGE_NO);
51
52       end if;
53
54   procedure OUT_LEVEL(EQUIP_Y_OUT_LEVEL_SIM,EQUIP_Y_OUT_LEVEL,
55   EQUIP_X_OUT_LEVEL : in FLOAT) is
56
57   begin -- This Procedure contains some of the diagnostic logic
58   -- for analyzing a substandard power output
59   MESSAGE_NO := 6;
60   -- PUT(" The OPERATIONAL DIAGNOSIS is:");
61   -- PUT(" the power output is ");
62   I_O_SIM_MODFAULT_MSG_LIST(MESSAGE_NO);
63   I_O_SIM_MODPARAM_OUT(EQUIP_Y_OUT_LEVEL);
64   if EQUIP_Y_OUT_LEVEL <= -90.0
65   then
66   MESSAGE_NO := 7;
67   -- PUT(" The reference oscillator level is below threshold ")
68   -- PUT(" so next pass choose the other oscillator.");
69   I_O_SIM_MODFAULT_MSG_LIST(MESSAGE_NO);
70
71   if EQUIP_Y_OUT_LEVEL <= EQUIP_Y_OUT_LEVEL_SIM
72   then
73     MESSAGE_NO := 8;
74     -- PUT("A degradation of output has occurred.");
75     -- PUT("caused by an output device failure.");

```

%ADAC-I-CL ADDED, Package body FAULT ANALYZE added to library  
%ADAC-I-CL ADDED, Package specification FAULT ANALYZE compiled 18-Jan-1987 21:22

אגדת חז"ל

there are no uses of potentially non-portable constructs

LIBRARY SUMMARY

USER2:[TELEADAPLIB]

ORIGINAL PAGE IS  
OF POOR QUALITY

```

1  {
2    EXPLAIN_DIAGNOSIS
3    {
4      {
5        {
6          with TYP_DEF_SIM; use TYP_DEF_SIM;
7          with I_O_SIM_MOD;
8
9        Package EXPLAIN_DIAGNOSIS is
10
11       procedure EXPLAIN_DIAGNOSIS(EQPT_Y, FREQ_SRC_A,FREQ_SRC_B : in SWITCH;-- Equipment sw's
12           REF_FREQ_LEVEL_A, REF_FREQ_LEVEL_B, -- Osc Out
13           EQUIP_Y_OUT_LEVEL_SIM, -- HW failure out level
14           EQUIP_X_OUT_LEVEL, -- Normal out Power
15           EQUIP_Y_OUT_LEVEL : in FLOAT;
16           EXPLAIN : in out CONTINUE);
17
18       end EXPLAIN_DIAGNOSIS;
19
20     PSECT MAP
21
22       Psctt Hex Size   Dec  Size   Name
23          0 00000020    32  EXPLAIN_DIAGNOSIS_.$CODE
24          1 0000000C    12  EXPLAIN_DIAGNOSIS_.$CONSTANT
25
26
27 %ADAC-I-CL ADDED, Package specification EXPLAIN DIAGNOSIS added to library
28 Replaces older version compiled 11-Jan-1987 02:22

```

#### PORTABILITY SUMMARY

There are no uses of potentially non-portable constructs

#### LIBRARY SUMMARY

USER2:[TFL.ADADIR.ADALIB]

Unit name	Nodes	Percent	Blocks	read	Unit kind
TYP_DEF_SIM	10	read	7		Package specification
I_O_SIM_MOD	4	7	5		Package specification

ORIGINAL PAGE IS  
OF POOR QUALITY

{ 61      .in\_}    nosi }

14  
15      Package body Explain\_Diagnosis is  
16  
17      procedure EXPLAIN\_DIAGNOSIS(EQPT\_Y, FREQ\_SRC\_A, FREQ\_SRC\_B : in SWITCH; -- Equipment sw/s  
18            REF\_FREQ\_LEVEL\_A, REF\_FREQ\_LEVEL\_B, -- Osc Out  
19            EQUIP\_Y\_OUT\_LEVEL\_SIM, -- HW failure out level  
20            EQUIP\_X\_OUT\_LEVEL, -- Normal Out Power  
21            EQUIP\_Y\_OUT\_LEVEL : in FLOAT;  
22            EXPLAIN : in out CONTINUE) is

23      MESSAGE\_NO : INTEGER; -- Local variable to contain number of msg  
24            -- for the message print procedure  
25  
26      -- This procedure provides an explanation of the reasoning behind the  
27      -- diagnosis of the equipment's ills.  
28      -- It is called from MAIN\_SIM.  
29  
30      begin  
31  
32  
33      MESSAGE\_NO := 10;  
34      I\_O\_SIM\_MOD.EXPLAIN\_MSG\_LIST(MESSAGE\_NO);-- Print Header  
35      if EQUIP\_Y\_OUT\_LEVEL <= -145.0  
36      then  
37        if EQPT\_Y = ON  
38        then  
39          MESSAGE\_NO := 11;  
40          -- The output measured was very low and noisy.);  
41          -- Yet the master switch was ON.);  
42          -- Obviously was some other failure.);  
43          I\_O\_SIM\_MOD.EXPLAIN\_MSG\_LIST(MESSAGE\_NO);  
44          if (FREQ\_SRC\_A=OFF) and (FREQ\_SRC\_B=OFF)  
45          then  
46            MESSAGE\_NO := 12;  
47            -- We then found both the oscillator switches were OFF, );  
48            -- so the malfunction was a set up error.);  
49          I\_O\_SIM\_MOD.EXPLAIN\_MSG\_LIST(MESSAGE\_NO);  
50      end if;

51      MESSAGE\_NO := 13;  
52      -- (We found the selected oscillator switch to be ON, );  
53      -- (so potentially we had a catastrophic oscillator failure.);  
54      I\_O\_SIM\_MOD.EXPLAIN\_MSG\_LIST(MESSAGE\_NO);  
55      end if;  
56  
57      MESSAGE\_NO := 14;  
58      -- (The master switch was found to be OFF so the malfunction);  
59      -- (was a set up error.)  
60      I\_O\_SIM\_MOD.EXPLAIN\_MSG\_LIST(MESSAGE\_NO);  
61      end if;  
62  
63      if EQUIP\_Y\_OUT\_LEVEL <= -90.0  
64      then  
65        MESSAGE\_NO := 15;  
66        -- (The out was between -145.0 dbm and -90.0 dbm. Thus the out );  
67        -- ( device was probably OK but the oscillator was below threshold.);  
68        -- (The oscillator out was insufficient to drive the out device);  
69        -- (Obviously on the next pass one should choose the other oscillator. )  
70      I\_O\_SIM\_MOD.EXPLAIN\_MSG\_LIST(MESSAGE\_NO);

11-Jan-1987 02:29:37 | -Jan 7 0 4 56 | <sup>X A</sup> <sup>L 3-</sup> | [TFL.ADADIR] EXPLAIN DIAGNOSIS.ADA;10 {<sup>3</sup>} (1)

```

71      else
72          if EQUIP_Y_OUT_LEVEL <= EQUIP_Y_OUT_LEVEL_SIM
73              then
74                  MESSAGE_NO := 16;
75                  --( A degradation of out had occurred, the out was above );
76                  --( -90.0 dbm but was still less than or equal to the out failure dbm. );
77                  --( This indicates that the selected oscillator was OK. );
78                  --( since some signal was 'leaking' through the circuitry. );
79                  --( but there was probably an out device Failure. );
80                  I_O_SIM_MOD.EXPLAIN_MSG_LIST(MESSAGE_NO);
81
82          else
83              if EQUIP_Y_OUT_LEVEL <= EQUIP_X_OUT_LEVEL
84                  then
85                      MESSAGE_NO := 17;
86                      --( Normal operation with normal or near normal out );
87                      --( since the out is above the out failure level. )
88                      I_O_SIM_MOD.EXPLAIN_MSG_LIST(MESSAGE_NO);
89                  end if;
90              end if;
91          end if;
92      end EXPLAIN_DIAGNOSIS;

```

卷之三

Name	Dec	Size	Dec	Size	Hex	Size	Dec	Size	Hex
Explain_Diagnosis.\$CODE	249		0	00000F9	0		0	00000000	
Explain_Diagnosis.\$CONSTANT	12		1	0000000C			1	00000001	
Explain_Diagnosis.\$DATA	1		2	00000000			2	00000002	

**IADAC-I-CL\_ADDED**, Package body EXPLAIN\_DIAGNOSIS added to library  
Replaces older version compiled 11-Jan-1987 02:22  
Corresponds to package specification EXPLAIN\_DIAGNOSIS compiled 11-Jan-1987 02:29

卷之三

and the constant rate of growth of the population.

TRADE SUMMARY

Unit name	Nodes	Percent read	Blocks read	Unit kind
EXPLAIN_DIAGNOSIS	16	100	1	Package specification
TYP_DEF_SIM	16	94	9	Package specification
__	7	9	1	Package specification

INITIAL\_SIM.DAT

OFF  
ACTIVE  
3.0  
-3.0  
-60.0  
0.0

ORIGINAL PAGE IS  
OF POOR QUALITY

```
{ }MAIN_SIM_MOD3
```

```
20-JAN-1987 0:52
```

```
Page 1
```

```
+-----+
! Object Module Synopsis :
```

Module Name	Ident	Bytes	File	Creation Date	Creator
ADA\$ELAB_MAIN_SIM_MOD3	01			20-Jan-1987 00:52	VAX Ada V1.3-23
TYP DEF SIM	01	82	[TFL.ADADIR]MAIN_SIM_MOD3.OBJ;1	17-NOV-1986 15:34	VAX Ada V1.3-23
IO EXCEPTIONS_	01	67	TYP DEF SIM_OBJ;2	6-MAR-1985 12:40	VAX Ada V1.0-7
Y_OUT_MOD_	01	6	[SYSLIB.ADALIB]IO_EXCEPTIONS_.OBJ;1	27-NOV-1986 00:25	VAX Ada V1.3-23
Y_OUT_MOD_	01	67	[TFL.ADADIR.ADALIB]Y_OUT_MOD_.OBJ;2	18-JAN-1987 22:18	VAX Ada V1.3-23
TEXT IO_	01	280	[TFL.ADADIR.ADALIB]Y_OUT_MOD_.OBJ;1	6-MAR-1985 12:42	VAX Ada V1.0-7
TEXT IO_	01	31	[SYSLIB.ADALIB]TEXT IO_.OBJ;1	6-MAR-1985 12:43	VAX Ada V1.0-7
I_O_SIM_MOD_	01	184	[SYSLIB.ADALIB]TEXT IO_.OBJ;1	11-JAN-1987 00:13	VAX Ada V1.3-23
I_O_SIM_MOD_	01	44	I_O_SIM_MOD_.OBJ;5	20-JAN-1987 00:51	VAX Ada V1.3-23
I_O_SIM_DIAGNOSIS	01	14608	I_O_SIM_MOD_.OBJ;14	11-JAN-1987 02:29	VAX Ada V1.3-23
EXPLAIN_DIAGNOSIS	01	44	EXPLAIN_DIAGNOSIS_.OBJ;5	11-JAN-1987 02:29	VAX Ada V1.3-23
FAULT_ANALYZE_	01	262	EXPLAIN_DIAGNOSIS OBJ;3	18-JAN-1987 21:22	VAX Ada V1.3-23
FAULT_ANALYZE_	01	44	FAULT_ANALYZE_.OBJ;3	18-JAN-1987 21:22	VAX Ada V1.3-23
LIB\$INITIALIZE	01	637	FAULT_ANALYZE_.OBJ;1	18-JAN-1987 22:31	VAX Ada V1.3-23
MAIN_SIM_MOD3	01	499	MAIN_SIM_MOD3.OBJ;1		

```
+-----+
! Program Section synopsis :
```

Psect Name	Module Name	Base	End	Length	Align	Attributes
\$CONSTANT		00000200	00001147	00000F48 (	3912.) LONG 2	PIC,USR,CON,REL,LCL, SHR, NOEXE,
	TYP DEF SIM_	00000200	0000020B	000000DC (	12.) LONG 2	RD, NOWRT, NOVEC
	Y_OUT_MOD_	0000020C	00000217	0000000C (	12.) LONG 2	
	Y_OUT_MOD_	00000218	00000223	0000000C (	12.) LONG 2	
	I_O_SIM_MOD_	00000224	0000022F	0000000C (	12.) LONG 2	
	I_O_SIM_MOD_	00000230	00001117	00000EE8 (	3816.) LONG 2	
	EXPLAIN_DIAGNOSIS	00001118	00001123	0000000C (	12.) LONG 2	
	EXPLAIN_DIAGNOSIS	00001124	0000112F	0000000C (	12.) LONG 2	
	FAULT_ANALYZE_	00001130	0000113B	0000000C (	12.) LONG 2	
	FAULT_ANALYZE_	0000113C	00001147	0000000C (	12.) LONG 2	
\$ZERO	TEXT IO_	00001200	00001207	00000008 (	8.) PAGE 9	PIC,USR,OVR,REL,LCL,
	I_O_SIM_MOD	00001200	00001207	00000008 (	8.) PAGE 9	SHR, NOEXE,
	LIB\$INITIALIZE	00001208	0000123B	00000034 (	52.) PAGE 9	RD, NOWRT, NOVEC
	ADA\$ELAB_MAIN_SIM_MOD3	00001208	0000123B	00000034 (	52.) LONG 2	
		00001400	0000144B	0000004C (	76.) LONG 2	PIC,USR,CON,REL,LCL,NOSH.R, NOEXE,
		00001400	00001400	00000001 (	1.) LONG 2	RD, WRT, NOVEC
		00001404	00001409	00000006 (	6.) LONG 2	
		0000140C	0000143F	00000034 (	52.) LONG 2	
	Y_OUT_MOD	00001440	00001440	00000001 (	1.) LONG 2	
	TEXT IO	00001444	0000144B	00000008 (	8.) LONG 2	
	I_O_SIM_DIAGNOSIS	00001444	0000144B	00000008 (		
	FAULT_ANALYZE	00001444	0000144B	00000008 (		

Project Name	Module Name	Base	End	Length	Align	Attributes
\$CODE		0001600	000480D	0000320E (	12814.) LONG 2	PIC,USR,CON,REL,LCL, SHR, EXE,
	ADA\$ELAB_MAIN_SIM_MOD3	0001600	000161D	0000001E (	30.) LONG 2	
	TYP DEF SIM	000161E	0001654	00000037 (	55.) BYTE 0	
	IO EXCEPTIONS	0001655	000165A	00000006 (	6.) BYTE 0	
	Y_OUT_MOD	000165B	0001691	00000037 (	55.) BYTE 0	
	Y_OUT_MOD	0001692	000179C	0000010B (	267.) BYTE 0	
	TEXT IO	000179D	00017B3	00000017 (	23.) BYTE 0	
	TEXT IO	00017B4	0001865	000000B2 (	178.) BYTE 0	
	I_O_SIM_MOD	0001866	0001885	00000020 (	32.) BYTE 0	
	I_O_SIM_MOD	0001886	0004278	000029F3 (	10739.) BYTE 0	
	EXPLAIN_DIAGNOSIS	0004279	0004298	00000020 (	32.) BYTE 0	
	EXPLAIN_DIAGNOSIS	0004299	0004391	000000FF9 (	249.) BYTE 0	
	FAULT_ANALYZE	0004392	00043B1	00000020 (	32.) BYTE 0	
	FAULT_ANALYZE	00043B2	000461A	00000269 (	617.) BYTE 0	
	MAIN_SIM_MOD3	000461B	000480D	000001F3 (	499.) BYTE 0	

+-----+  
: Symbols By Name :  
+-----+

Symbol	Value	Symbol	Value
ADA\$ELAB_MAIN_SIM_MOD3	0001600-R		

Key for special characters above:

+	*	-	U	R	X	V
+	*	-	U	R	X	V
+	Defined	Universal	Relocatable	External	Vectored	

Using a working set limited to 1350 pages and 686 pages of data storage (excluding image)

THE JOURNAL OF CLIMATE

actual number of objects read (both passes): 944

initially were written in libraries and were DEBUG data records containing 26139 bytes

Number of modules extracted explicitly = 0

with 2 extracted to resolve undefined symbols

U library searches were for symbols not in the library searched

A *total* *of* *6* *or* *7* *days*

total of 5 global symbol table records was written

LINK /MAP= | MAIN SIM MOD3 /EXE= | MAIN SIM MOD3 EXECUTABLE

POLY(1,4-BUTADIENE) SISYLICATE: POLYMERIZATIONS